A posteriori error estimation in the FEniCSx finite element software and application to the fractional Laplacian.

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#### 2010-2013 Bachelor in Mathematics

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## 2014 CAPES (competitive exam)

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## 2015-2017 Master in Advanced Mathematics at Université de Bourgogne Franche-Comté. 2016 Agrégation (competitive exam) of Mathematics. 2014 CAPES (competitive exam) of Mathematics. 2010-2013 Bachelor in Mathematics

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## 2015-2017 Master in Advanced Mathematics

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A reaction diffusion problem

Let 
$$f\in L^2(\Omega)$$
 and  $a\in \mathbb{R}^{+*}$ , we look for  $u$  s.t

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In weak formulation, find u in  $H_0^1(\Omega)$  such that

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Lagrange finite element discretization of order k, find  $u_k$  in  $V^k$  such that

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**Goal:** estimate  $\eta_{\text{err}} = |||u_k - u|||_{\Omega}$  i.e. find a computable quantity  $\eta_{\text{bw}}$  such that  $\eta_{\text{bw}} \approx \eta_{\text{err}}$ .

Definition

On a cell T, the Bank–Weiser problem is given by: find  $e_T^{\text{bw}}$  in  $V_T^{\text{bw}}$  such that

$$\int_T e_T^{\mathrm{bw}} v_T^{\mathrm{bw}} + a \int_T \nabla e_T^{\mathrm{bw}} \cdot \nabla v_T^{\mathrm{bw}} = \int_T r_T v_T^{\mathrm{bw}} + \sum_{E \in \partial T} \frac{1}{2} \int_E J_E v_T^{\mathrm{bw}} \quad \forall v_T^{\mathrm{bw}} \in V_T^{\mathrm{bw}}.$$

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The Bank–Weiser estimator is defined as

$$\eta_{\mathrm{bw}}^2 := \sum_{T \in \mathcal{T}} \eta_{\mathrm{bw},T}^2, \quad \eta_{\mathrm{bw},T} := |||e_T^{\mathrm{bw}}||_T.$$

Definition

What is  $V_T^{\text{bw}}$  ? Let  $V_T^- \subsetneq V_T^+$  be two finite element spaces and

$$\mathcal{L}_T: V_T^+ \longrightarrow V_T^-,$$

be the local Lagrange interpolation operator,

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since  $V_T^+$  is provided by DOLFIN/x and we look for a matrix N such that:

$$A_T^{\mathrm{bw}} = N^{\mathsf{t}} A_T^+ N$$
, and  $b_T^{\mathrm{bw}} = N^{\mathsf{t}} b_T^+$ .

Implementation



Implementation



Implementation



# The Bank–Weiser estimator Pros and cons Pros

Pros and cons

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#### Local efficiency

$$\begin{split} \eta_{\mathrm{bw},T} &\leqslant C\eta_{\mathrm{err},T} + \mathrm{h.o.t.}_{|_{T}} \\ \text{[Bank and Weiser, 1985, Nochetto, 1993,} \\ \text{Verfürth, 1994].} \end{split}$$

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 $\label{eq:relation} \begin{array}{l} \mbox{Reliability } \eta_{err} \leqslant c\eta_{bw} + {\rm h.o.t.} \\ \mbox{under some conditions} \\ \mbox{[Bank and Weiser, 1985, Nochetto, 1993, Verfürth, 1994, Bulle et al., 2021].} \end{array}$ 

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Flexible & Robust w.r.t. parameters of the problems [Verfürth, 1989, Verfürth, 1998, Verfürth, 1999, Verfürth, 2005, Liao and Silvester, 2012, Khan et al., 2019, Bulle et al., 2021, Bulle et al., 2022]. Cons

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Not robust w.r.t. the choice of the space  $V_T^{\rm bw}$  or the polynomial degree [Ainsworth, 1994].

No convergence proof when used for adaptive mesh refinement [Carstensen et al., 2014].

Numerical results

Adaptive finite elements for a Poisson problem:  $-\Delta u = 0$  in  $\Omega$ ,  $u = u_D$  on  $\Gamma$ . Linear finite elements.


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Adaptive finite elements for a Poisson problem:  $-\Delta u = 0$  in  $\Omega$ ,  $u = u_D$  on  $\Gamma$ . Quadratic finite elements.



Numerical results

#### GO AFEM for a linear elasticity problem:

we used a technique from [Khan et al., 2019] and [Becker et al., 2011] to compute the estimators. The goal functional is defined by  $J(\mathbf{u},p) := \int_{\Gamma} \mathbf{u} \cdot \mathbf{n}c$ , where c is a Gaussian weight centered on the middle of the bone.



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Numerical results

#### Timescale study:

strong scaling study on the Uni Lu cluster [Varrette et al., 2014].  $-\Delta u = f$  on  $[0,1]^3$ , u = 0 on  $\Gamma$ .  $\mathcal{P}_2$  Lagrange elements. The Bank–Weiser estimator is  $\eta_{\mathrm{bw}}^{3,2}$ . The problem size is fixed around 135 million dof.





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- Main drawback: they are nonlocal.

Problem setting

Let 
$$\Omega \subset \mathbb{R}^d$$
,  $s \in (0,1)$  and  $f \in L^2(\Omega)$ .  
 $(-\Delta)^s u = f \quad \text{in } \Omega, \qquad u = 0 \quad \text{on } \Gamma.$ 

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The solution u is defined by

$$u := \sum_{i=1}^{+\infty} \lambda_i^{-s} (f, \psi_i)_{L^2},$$

where  $\{\psi_i, \lambda_i\}_{i=1}^{+\infty} \subset L^2(\Omega) \times \mathbb{R}^+$  is the spectrum of  $-\Delta$ .

#### The spectral fractional Laplacian Problem setting

The natural space associated with this problem is

$$\mathbb{H}^{s}(\Omega) := \left\{ v \in L^{2}(\Omega), \sum_{i=1}^{+\infty} \lambda_{i}^{s} \left( v, \psi_{i} \right)_{L^{2}}^{2} < +\infty \right\},$$

of norm 
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If  $f \in L^2(\Omega)$ , then  $u \in \mathbb{H}^{2s}(\Omega)$  and

$$||u||_{\mathbb{H}^{2s}}^2 = ||f||_{L^2}^2.$$

Discretization

$$(-\Delta)^s u = f \text{ in } \Omega, \qquad u = 0 \text{ on } \Gamma.$$

How to solve this equation numerically ?

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How to solve this equation numerically ?

$$u := (-\Delta)^{-s} f = \sum_{i=1}^{+\infty} \lambda_i^{-s} (f, \psi_i)_{L^2},$$

we use a rational approximation

$$\lambda^{-s} \simeq \mathcal{Q}_s^N(\lambda) := C_s(N) \sum_{l=1}^N a_l (1+b_l \lambda)^{-1}, \qquad \forall \lambda \in [\lambda_1, +\infty),$$

where  $(a_l)_l$  and  $(b_l)_l$  are positive coefficients and  $C_s(N)$  is independent of  $\lambda$ .

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$$\simeq C_s(N) \sum_{l=1}^N a_l (\mathrm{Id} - b_l \Delta)^{-1} f = C_s(N) \sum_{l=1}^N a_l u_l.$$

Discretization

$$(-\Delta)^{s} u = f, \quad \text{in } \Omega, \qquad \qquad \text{For } l = 1, \cdots, N,$$

$$(-\Delta)^{s} u = f, \quad \text{in } \Omega, \qquad \qquad u_{l} - b_{l} \Delta u_{l} = f, \quad \text{in } \Omega, \quad (1)$$

$$u = 0, \quad \text{on } \Gamma. \qquad \qquad u_{l} = 0, \quad \text{on } \Gamma. \quad (2)$$

Discretization

We denote  $u \simeq u_{\mathcal{Q}_s^N} := C_s(N) \sum_{l=1}^{r} a_l u_l$ . However,  $u_{\mathcal{Q}_s^N}$  is not a discrete function.

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$$\int_{\Omega} u_l v + b_l \int_{\Omega} \nabla u_l \cdot \nabla v = \int_{\Omega} f v, \qquad \forall v \in H_0^1(\Omega), \, \forall l \in [\![1, N]\!],$$

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$$\begin{split} &\int_{\Omega} u_l v + b_l \int_{\Omega} \nabla u_l \cdot \nabla v = \int_{\Omega} f v, \qquad \forall v \in H_0^1(\Omega), \ \forall l \in [\![1, N]\!], \\ &\text{and write its FE discretization} \\ &\int_{\Omega} u_{l,k} v_k + b_l \int_{\Omega} \nabla u_{l,k} \cdot \nabla v_k = \int_{\Omega} f v_k, \qquad \forall v_k \in V^k, \ \forall l \in [\![1, N]\!]. \end{split}$$

Discretization

Solving these classical FE problems we finally get a fully discrete approximation of  $\boldsymbol{u}$ 

$$u \simeq u_{\mathcal{Q}_s^N} := C_s(N) \sum_{l=1}^N a_l u_l \simeq C_s(N) \sum_{l=1}^N a_l u_{l,k} =: u_{\mathcal{Q}_s^N}^k$$

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#### Advantages of this method:

- it is easily parallelizable,
  - it involves "standard" FE machinery,
- it is well-suited to three-dimensional problems.

Error estimation

#### How can we bound the discretization error ?

$$\|u - u_{\mathcal{Q}_s^N}^k\| \leqslant \|u - u_{\mathcal{Q}_s^N}\| + \|u_{\mathcal{Q}_s^N} - u_{\mathcal{Q}_s^N}^k\|.$$
  
where  $\|\cdot\| = \|\cdot\|_{L^2}$ , or  $\|\cdot\|_{\mathbb{H}^s}$ .

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Quantification of the rational approximation error  $||u - u_{Q_s^N}||$ .

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then, [Bonito and Pasciak, 2015]

$$\|u - u_{\mathcal{Q}_s^N}\|_{L^2} \leqslant \varepsilon_s(N) \|f\|_{L^2}.$$

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Moreover, if  $f\in \mathbb{H}^{s}(\Omega)$  then [Bonito and Pasciak, 2016]

$$\|u - u_{\mathcal{Q}_s^N}\|_{\mathbb{H}^s} \leqslant \varepsilon_s(N) \|f\|_{\mathbb{H}^s}.$$
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Moreover, if  $f\in \mathbb{H}^{s}(\Omega)$  then [Bonito and Pasciak, 2016]

$$\|u - u_{\mathcal{Q}_s^N}\|_{\mathbb{H}^s} \leqslant \varepsilon_s(N) \|f\|_{\mathbb{H}^s}.$$

In particular, there exists an approximation  $Q_s^N$  such that  $\varepsilon_s(N)$  is fully computable and [Bonito and Pasciak, 2015]

$$\varepsilon_s(N) = \mathcal{O}_{N \to +\infty} \left( e^{-\left(\pi^2/2\sqrt{2}\right)\sqrt{N}} \right)$$

Error estimation

Quantification of the rational approximation error  $||u - u_{Q_s^N}||$ .

Conjecture:  $||u - u_{\mathcal{Q}_s^N}||_{\mathbb{H}^s} \leq \varepsilon_s(N) ||f||_{L^2}$ .

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.

What we can prove [Bulle, 2022]:

$$\|u - u_{\mathcal{Q}_s^N}\|_{\mathbb{H}^s} \leqslant \widetilde{\varepsilon}_s(N) \|f\|_{L^2},$$

where  $\widetilde{\varepsilon}_s(N) \xrightarrow[N \to +\infty]{} 0$  with a possibly slower convergence rate than  $\varepsilon_s$ .

Error estimation

Quantification of the finite element error  $||u_{Q_s^N} - u_{Q_s^N}^k||$ .

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  - A posteriori error estimate for  $\|\cdot\|_{\mathbb{H}^s}$  is an ongoing work.

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For each cell  $T \in \mathcal{T}_h$  and each parametric problem  $l \in [\![1, N]\!]$ , we solve the Bank–Weiser equation to estimate the difference

$$u_{l|_T} - u_{l,k|_T} \simeq e_{l,T}^{\mathrm{bw}}.$$

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Then,

$$\left(u_{\mathcal{Q}_{s}^{N}}-u_{\mathcal{Q}_{s}^{N}}^{k}\right)_{|_{T}}=C_{s}(N)\sum_{l=1}^{N}a_{l}(u_{l}-u_{l,k})\simeq C_{s}(N)\sum_{l=1}^{N}a_{l}e_{l,T}^{\mathrm{bw}}=:e_{\mathcal{Q}_{s}^{N},T}^{\mathrm{bw}},$$

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and finally, we expect that:

$$\|u_{\mathcal{Q}_s^N} - u_{\mathcal{Q}_s^N}^k\|_{L^2}^2 \simeq \|e_{\mathcal{Q}_s^N}^{\text{bw}}\|_{L^2}^2 = \sum_{T \in \mathcal{T}} \|e_{\mathcal{Q}_s^N, T}^{\text{bw}}\|_{L^2(T)}^2.$$

Adaptive mesh refinement

Fractional Laplacian problems show a particular sensibility to **boundary** layers effect. Thus, even for smooth data, the mesh might need to be adaptively refined near the boundary  $\Gamma$  [Banjai et al., 2019].

Adaptive mesh refinement

Fractional Laplacian problems show a particular sensibility to **boundary layers effect**. Thus, even for smooth data, the mesh might need to be adaptively refined near the boundary  $\Gamma$  [Banjai et al., 2019]. We can use the Bank–Weiser error estimator to steer an adaptive refinement algorithm.

### Adaptive mesh refinement

Choose a tolerance  $\delta > 0$ , an initial mesh  $\mathcal{T}_{n=0}$  and N such that  $\varepsilon_s(N) \|f\|_{L^2} \ll \delta$ Generate the rational approximation  $\mathcal{Q}_s^N$  coefficients Initialize the estimator  $\eta_{\mathcal{Q}_N}^{\mathrm{bw}} = \delta + 1$ 

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 $\begin{array}{l} \label{eq:powerset} \mbox{While } \eta^{\rm bw}_{\mathcal{Q}^N_s} > \delta : \\ & \mbox{Initialize the solution } u_{\mathcal{Q}^N_s,k} = 0 \\ & \mbox{Initialize the local Bank-Weiser solutions } \{e^{\rm bw}_{\mathcal{Q}^N,T} = 0\}_T \end{array}$ 

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Choose a tolerance  $\delta > 0$ , an initial mesh  $\mathcal{T}_{n=0}$  and N such that  $\varepsilon_s(N) \|f\|_{L^2} \ll \delta$ Generate the rational approximation  $\mathcal{Q}^{\scriptscriptstyle N}_{\scriptscriptstyle \rm s}$  coefficients Initialize the estimator  $\eta_{O^N}^{\text{bw}} = \delta + 1$ 

```
While \eta_{\mathcal{O}^N}^{\text{bw}} > \delta:
    Initialize the solution u_{\mathcal{Q}_{n,k}^{N}} = 0
    Initialize the local Bank–Weiser solutions \{e_{\mathcal{Q}_{n,T}^{N}}^{\text{bw}}=0\}_{T}
    For each parametric problem l \in [\![1, N]\!]:
            Solve parametric problem on \mathcal{T}_n to obtain u_{l,k} Add u_{\mathcal{Q}_s^N,k}+C_s(N)a_lu_{l,k}
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Add 
$$u_{\mathcal{Q}_s^N,k} + C_s(N)a_lu_{l,k}$$

For each cell T of  $\mathcal{T}_n$ :

 $\begin{array}{|c|c|c|c|} & \text{Solve BW local parametric problem on } T \text{ to obtain } e^{\text{bw}}_{l,T} \\ & \text{Add } e^{\text{bw}}_{\mathcal{Q}^N,T} + C_s(N) a_l e^{\text{bw}}_{l,T} \end{array}$ 

### Adaptive mesh refinement

Choose a tolerance  $\delta > 0$ , an initial mesh  $\mathcal{T}_{n=0}$  and N such that  $\varepsilon_s(N) \|f\|_{L^2} \ll \delta$ Generate the rational approximation  $Q_s^N$  coefficients Initialize the estimator  $\eta_{O^N}^{\text{bw}} = \delta + 1$ While  $\eta_{\mathcal{O}^N}^{\text{bw}} > \delta$ : Initialize the solution  $u_{\mathcal{Q}_s^N,k} = 0$ Initialize the local Bank–Weiser solutions  $\{e_{\mathcal{O}^N,T}^{\text{bw}}=0\}_T$ For each parametric problem  $l \in [\![1, N]\!]$ : Solve parametric problem on  $\mathcal{T}_n$  to obtain  $u_{l,k}$ Add  $u_{\mathcal{Q}_s^N,k} + C_s(N)a_lu_{l,k}$ For each cell T of  $\mathcal{T}_n$ : Solve BW local parametric problem on T to obtain  $e^{\rm bw}_{l,T}$  Add  $e^{\rm bw}_{Q^N,T}+C_s(N)a_le^{\rm bw}_{l,T}$ Compute  $\{\eta_{\mathcal{Q}_{n}^{N},T}^{\mathrm{bw}} = \|e_{\mathcal{Q}_{n}^{N},T}^{\mathrm{bw}}\|_{L^{2}(T)}\}_{T}$ Take the square root of the sum of  $\{\eta_{Q_T}^{\text{bw}}, T^2\}_T$  to obtain  $\eta_{Q_T}^{\text{bw}}$ 

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Numerical results

 $(-\Delta)^s u = f$ , in  $[0,1]^2$ , u = 0, on  $\Gamma$ , with f(x,y) = 1 in  $[0,0.5]^2 \cup [0.5,1]^2$ , -1 otherwise. We assume the rational approximation is negligible, i.e.  $u = u_{Q_s^N}$ .



### Numerical results



Numerical results

 $(-\Delta)^s u = f$ , in  $[0,1]^3$ , u = 0, on  $\Gamma$ . We assume the rational approximation is negligible, i.e.  $u = u_{Q_1^N}$ .



### Numerical results



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# Thank you for your attention!



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